APPENDIX 1

```
void sw ( )
(

#define iw = 12;                                  /* instruction
                                                   width */

#define mw = 3:                                   /* memory width */
#define CONST = 0                                 /* push constant */
#define LOAD = 1                                  /* push variable */
#define GLOBAL = 2                                /* push address */
#define PUTCHAR, = 15 /*                          put a character along the
                                                   standard output channel*/

#define GETCHAR = 16 /*                           get a character from the
                                                   standard input channel */


...

rom program []
#include "prog.o" ): ram stack[1«mw] with dualport = 1 ];
ram memory[1«mw] unsigned iw PC, ir, tos;
unsigned mw sp;

do par it = program[pc]: PC = PC + 1;
tos = stack[sp-1];                                /* save top of
                                                   stack to avoid
                                                   two ram accesses
                                                   in one cycle
                                                   */


switch (ir)
case
CONST par
        stack[sp] = program[pc];
        sP = sP+1:
        PC = Pc+1:
        ]
        break;
case LOAD
        stack[sp-1] = memory[tos<-mw];
        break;
case STOP break; default :                        /* unknown opcode */
while (1) delay;

] while (ir != STOP);
```

]

Register transfer level description of simple processor

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APPENDIX 2

```
void main() { char hwswchan;
char unsigned 8 port:

        par {
                parallel_,,port(port);
                SyncGen():

                        initialiseRam(port);
                        par {
                                display(hwswchan): sw(hwswchan);
                                y 1 }
        }

        RTL description of main
```

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APPENDIX 3

CALCULATION PROCESS

```
5      /*
       * Channel communicating object positions
       */ chap unsigned 17 position;


       /*
10     * Channel communicating segment information
       */
       chanout unsigned 9 segment;


       /*
15     * Channel communicating button information
       */
       chanin unsigned 2 buttons;


       /*
20     * Overall par
       */ par

                  /*
                  * Mass motion
25                */

                        /*
                        * Positions of each mass, 9+8 fixed point
                         */
30                      unsigned 17 p0, pl, p2, p3, p4, p5, p6, p7;
                        /*
                        * Velocity of each mass, 9+8 fixed point
                         */
                        int 17 vl, v2, v3, v4, v5, v6, v7; '
35                      /*
                        * Accelerations of each mass, 9+8 fixed point
                         */
                        int 17 al, a2, a3, a4, a5, a6, a7;
                        /*
40                      * Sutton status
                         */
                        unsigned 2 button status;
                        /*
                        * Initial setup of positions
45                       */
```

```
p0 = 65536;
p1 = 65536;
p2 = 65536;
p3 = 65536;
p4 = 65536;
p5 = 65536;
p6 = 65536
p7 =65536


/*
* Forever
*/
while (1)
    {

    /*
     * Send successive positions down position channel
     */
    send(position, p0);
    send(position, p1);
    send(position, p1);
    send(position, p2);
    send(position, p2);
    send(position, p3);
    send (position, p3);
    send(position, p4);
    send(position, p4);
    send(position, p5);
    send(position, p5);
    send(position, p6);
    send(position, p6);
    send(position, p7);

    /*
    * Update positions according to velocities
     */
    p1 +_ (unsigned 17)v1;
    p2 +_ (unsigned 17)v2;
    p3 +_ (unsigned 17)v3;
    p4 +_ (unsigned 17)v4;
    p5 +_ (unsigned 17)v5;
    p6 +_ (unsigned 17)v6;
    p7 +_ (unsigned 17)v7;

        /*
```

```
                     * Update velocities according to accelerations
                     */
                    vl += al - (v1 » 6);
                    v2 += a2 - (v2 » 6) ;
        5           v3 += a3 - (v3 » 6);
                    v4 += a4 - (v4 » 6);
                    v5 += a5 - (v5' » 6);
                    v6 += a6 - (v6 » 6);
                    v7 += a7 - (v7 » 6);
       10
                    /*
                     * Set accelerations according to relative positions
                     */
                    a1 = (int 17)(((p2 » 8) - (pl » 8)) + ((p0 » 8) - (pl » 8)));
       15           a2 = (int 17)(((p3 » 8) - (p2 » 8)) + ((pl » 8) - (p2 » 8))):
                    a3 = (int 17)!!(p4 » 8) - (p3 » 8)) + ((p2 » 8) - !p3 » 8)));
                    a4 = (int 17)(((p5 » 8) - (p4 » 8)) + ((p3 » 8) - (p4 » e> >;
                    a5 = (int 17)((!p6 » 8) - (p5 » 8)) + ((p4 » 8) - (p5 » 8)));
                    a6 = (int 17)(((p7 » 8) - (p6 » 8)) + ((p5 » 8) - (p6 » e > ) ;
       20           a7 = (int 17)((p6 » 8) - (p7 » 8));

                    /*
                     * Get button information
                     */
       25           receive(buttons, button status);

                    /*
                     * Fix top point according to buttons
                     */ if (button status & 1)
       30
                        p0 = 65536 - 16384;
                        )
        else        if (button status & 2)
                        (
       35                 p0 = 65536 + 16384;

        else

                            p0 = 65536;
       40               }
                    )
                    /*
                     * nine drawing
                     */
       45           (
                        /*
```

```
  * Positions of previous and next massess positions
  */
 unsigned 17 prev_.pos, next pos, curr pos;
 /*
  * Which line of interpolation
  */
 unsigned char line;
 /*
  * Forever
  */
 while (1)
    (
    /*
     * Receive previous mass position
     */
    receive (position, prev posy;
    curr pos = prev pos;
    /*
     * Read next mass position
     */
    receive(position, next posy;
    /*
     * Do 64 lines of interpolation
     */
    for (line = 0; line != 64; line++)
       (
       /*
        * Send start position of segment
        */
       send(segment, curr pos » 8);      /**width adjustment:17 along
                                            channel of width 9 so takes bottom 9
                                            bits*/

       /*
        * Move by appropriate amount (1/64  total change)
        */
       curr pos +_ (unsigned 17)(((int 17)next pos -
                                  (int 17)prev pos) » 6);
       /*
        * Send end position of segment
        */
       send(segment, curr pos » 8):
       )
    )
 )
)
```

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DISPLAY PROCESS

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```
/* standard includes */
        #include "hammond.h"
    #include "syncgen.h"
    #include "stdlib.h"
10  #include "parallel.h"


        /*
* Segment information channel */ chap segment;

15       /*
* Button information channel */
chan buttons:


        /
20  * Include dash generated stuff */
#include "handelc.h"


        /*
* Main program */
25  void main() (
        /
* Scan positions
*/ unsigned sx, sy;

30       /
* Vdeo output register
*/
unsigned 1 video;

35       /*
* Video output bus
*/

interface bus out() video out(Visible(sx, sy) ?
40  (video ? (unsigned 12)Oxfff : 0) 0) with video spec;

#ifndef SIMULATE
        /*
* Left button input bus
45  */
interface bus in (unsigned 1) button_left()
```

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```
                with button white spec;

        /*
        * Right button input bus
 5      */
                interface bus in(unsigned 1) button right()
                    with button_black spec;
            #endif

10      /*
        *
                Overall par
        */ par {
        /*
15              * VGA sync generator
                */
            SyncGen(sx, sy, hsync pin, vsync pin);
            /*
             *
20              Dash generated hardware
            */
            hardware();
            /*
             * Run-length decoder
25          */
            {
            /*
             * Segment start and end positions
             * /
30      unsigned start, end;
            /*
             * Forever
            */
            while (1)
35            {
                while (sy != 448)
                  /*
                   * Read segment information
                   */
40                segment ? start;
                  segment ? end;
                  /*
                   * Get in the right order
                   */
45                if (start > end)
                     {
```

```
                              par
                                {

        end = start;
  5     start = end;.
        )



                             /*
 10     * Make at least 1 pixel visible
        */
        if (start == end)
                            end++;

 15     /*
                            * Wait
        */
                        while (sx != 0)
                          delay;
 20                     /*
                         * Draw a scanline worth
                         * /
                        while (sx != 512)
                            if ((sx <- 9) >= start && (sx <- 9) < end)
 25
                                video = 1;
                              else
                            video = 0;

 30                         )
                    /*
                     * Communicate button status
                     */
        #ifdef SIMULATE
 35                     buttons ! 1;
        #else
                        buttons ! button left.in @ button right.in;
        #endif
                    /*
 40                  * Wait
                      */
                    while (sy != 0)
                      delay;
                )
 45
```

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